

# Seasonal hydropower scheduling using linear decision rules

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# Agenda

- LDR approximation vs scenarios
- Modelling considerations
- Description of benchmarking
- How does LDR perform?
- Analysis of results
  
- ~~Uncertainty modelling~~
- ~~Mathematical transformations~~
- ~~How head was included~~
- ~~How water values was calculated~~

# Problem and solution method

- Seasonal Hydro Power Planning Problem
  - Weekly resolution
  - Uncertainty in price and inflow
  - Plan power generation, pumping, bypass
  - For input to short-term models
- Linear Decision Rules
  - Affine reaction functions

$$\begin{aligned}
 \max \quad & T^H \sum_{t \in \mathcal{T}} \beta_t \pi_t \sum_{r \in \mathcal{R}} \sum_{d \in \mathbb{D}} E_{rt}^d x_{rt}^d \\
 \text{s.t.} \quad & m_{r0} = M_r^0 \quad r \in \mathcal{R} \\
 & m_{rt} = m_{r(t-1)} + F_{rt} + T^S \sum_{d \in \mathbb{D}} \left( \sum_{\rho \in \mathbb{C}_r^d} x_{\rho t}^d - x_{rt}^d \right) \quad r \in \mathcal{R}, t \in \mathcal{T} \\
 & \underline{M}_{rt} \leq m_{rt} \leq \overline{M}_{rt} \quad r \in \mathcal{R}, t \in \mathcal{T} \\
 & L_{rt}^q \leq E_{rt}^q x_{rt}^q \leq U_{rt}^q \quad r \in \mathcal{R}, t \in \mathcal{T} \\
 & L_{rt}^p \leq E_{rt}^p x_{rt}^p \leq U_{rt}^p \quad r \in \mathcal{R}, t \in \mathcal{T} \\
 & \underline{D}_{rt} \leq x_{rt}^q + C_{rt}^B \leq \overline{D}_{rt} \quad r \in \mathcal{R}, t \in \mathcal{T} \\
 & x_{rt}^s \geq 0 \quad r \in \mathcal{R}, t \in \mathcal{T}
 \end{aligned}$$

# Problem and solution method

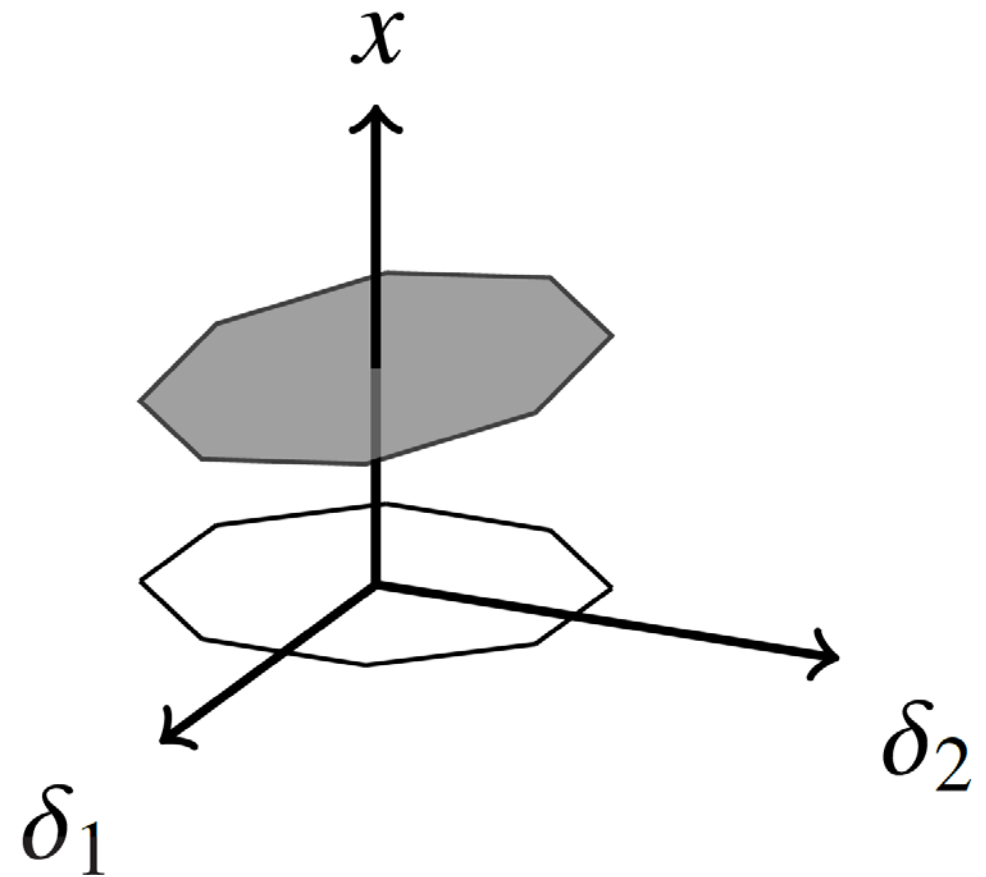
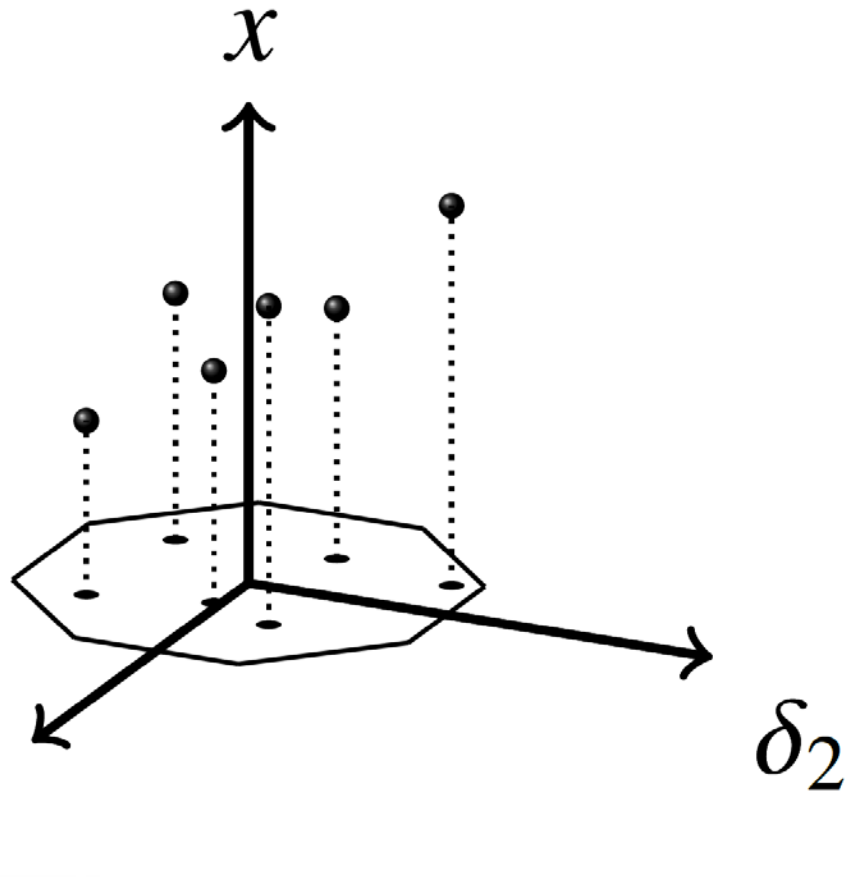
- Seasonal Hydro Power Planning Problem
  - Weekly resolution
  - Uncertainty in price and inflow
  - Plan power generation, pumping, bypass
  - For input to short-term models
- Linear Decision Rules
  - Affine reaction functions
  - Policy: Intercept + slope

$$\mathbf{x}(\delta) = \hat{\mathbf{x}} + K^x \delta$$

Diagram illustrating the affine reaction function  $\mathbf{x}(\delta) = \hat{\mathbf{x}} + K^x \delta$ . The components are labeled as follows:

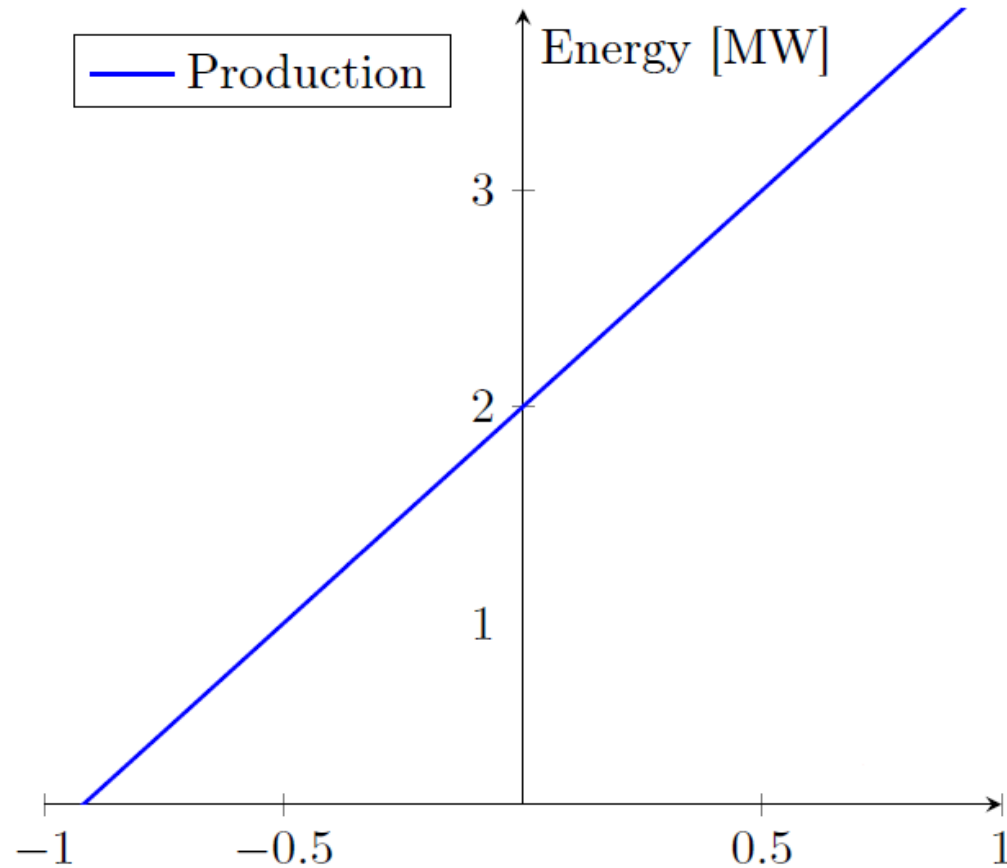
- $\hat{\mathbf{x}}$ : Intercept
- $K^x$ : Slope
- $\delta$ : Uncertainty parameter
- $\mathbf{x}(\delta)$ : Decision rule

# LDR approximation



# Modelling considerations 1

## Zero-mean uncertainty



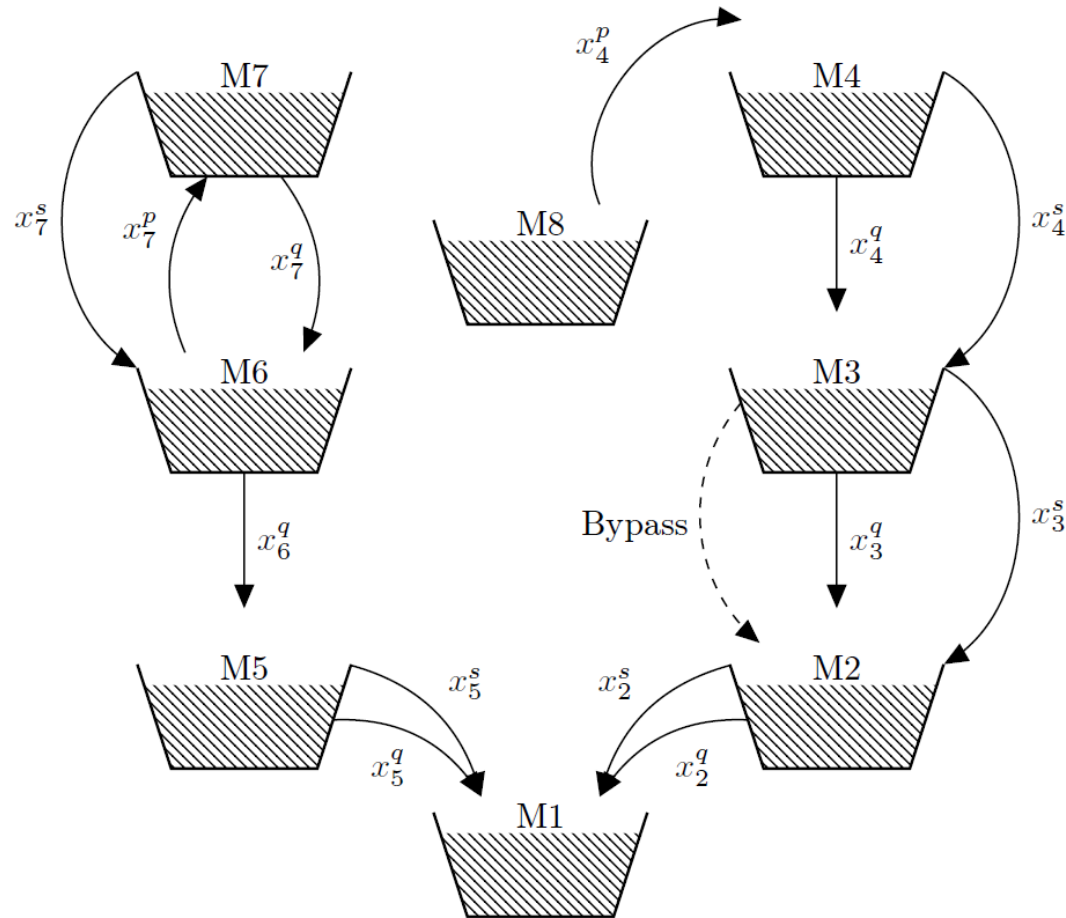
# Modelling considerations 2

## Memory sets

- On what time periods can the decisions react?
- Solution time vs. optimality gap
- Smart memory sets

# Benchmarking

## Description of test case





# Benchmarking

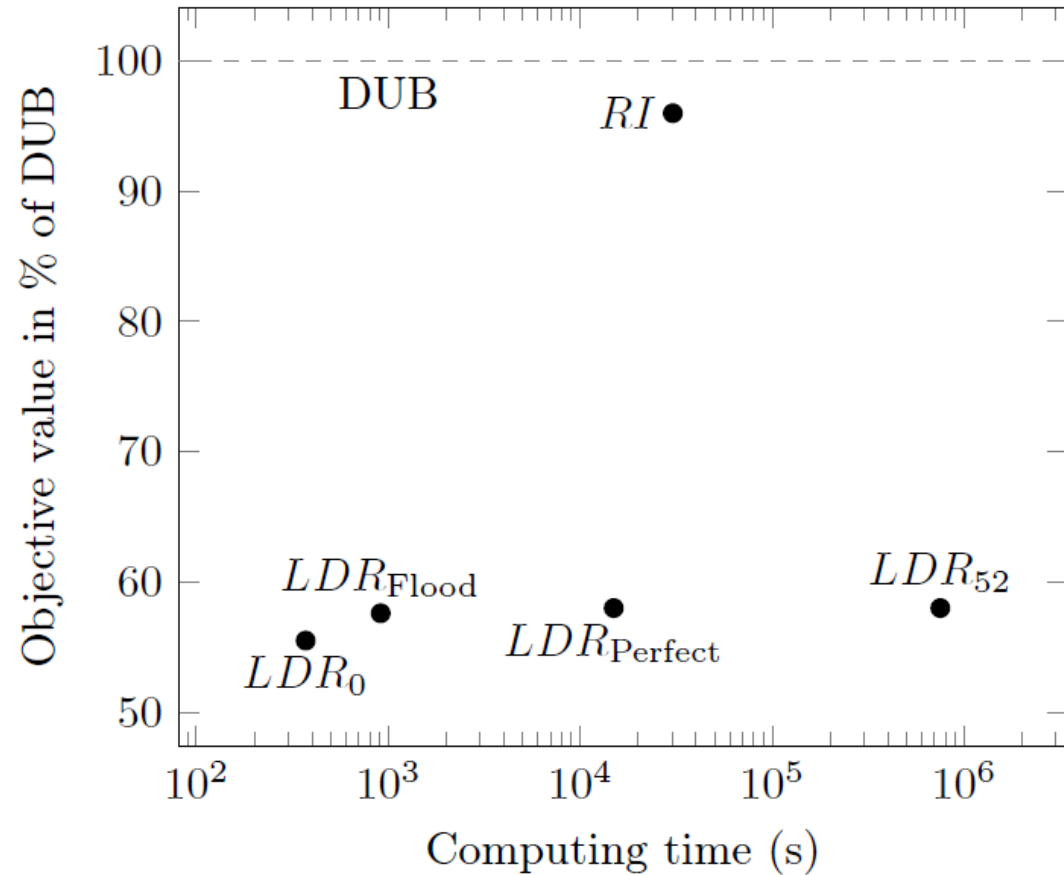
## Description of testing

- **Solution methods**
  - Linear Decision Rules (LDR)
    - Different memory sets
  - Rolling Intrinsic (RI)
  - Dual Upper Bound (DUB)
- Simulated policies on 3000 scenarios

# Results Analysis

- Computing time
  - Different memory sets
  - Compared to RI
- Solution quality
  - Optimality gap
- Why?

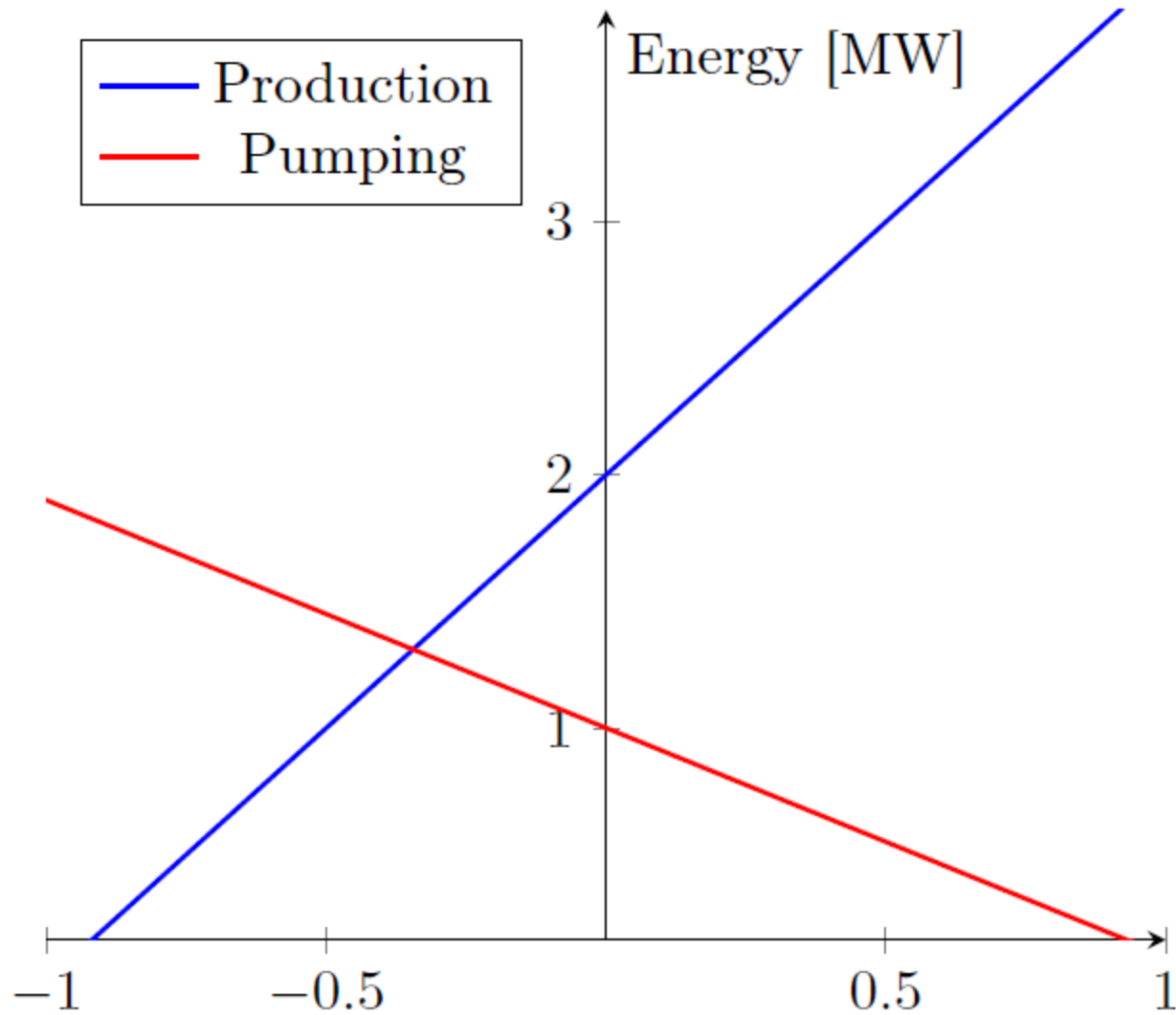
$$\mathbf{x}(\delta) = \hat{\mathbf{x}} + K^x \delta$$



# Results Analysis

- *Linear* Decision Rules

# Results Analysis



# Results Analysis

- *Linear* Decision Rules
- Further research
  - Piecewise Linear Decision Rules
  - Historically based memory sets

# Conclusion

- Know the strengths of LDR
  - Swift on smaller memory sets
  - Potential in piece-wise LDR
- Be aware of the limitations of LDR
  - Loss of optimality
  - Linearity of model

# Thank you!

Our master thesis:

<https://daim.idi.ntnu.no/masteroppgave?id=13112>

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# Attachments



# Heat maps

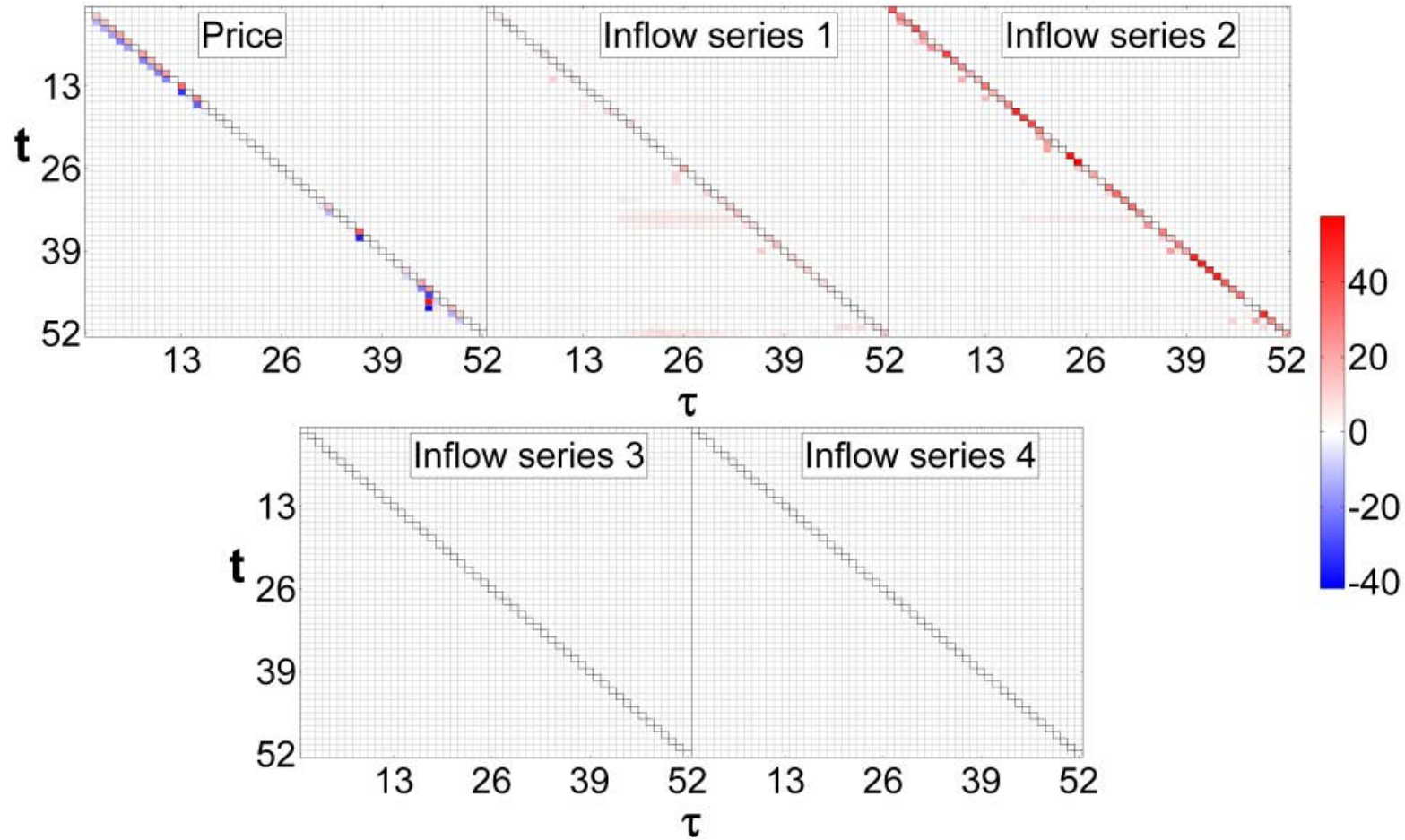
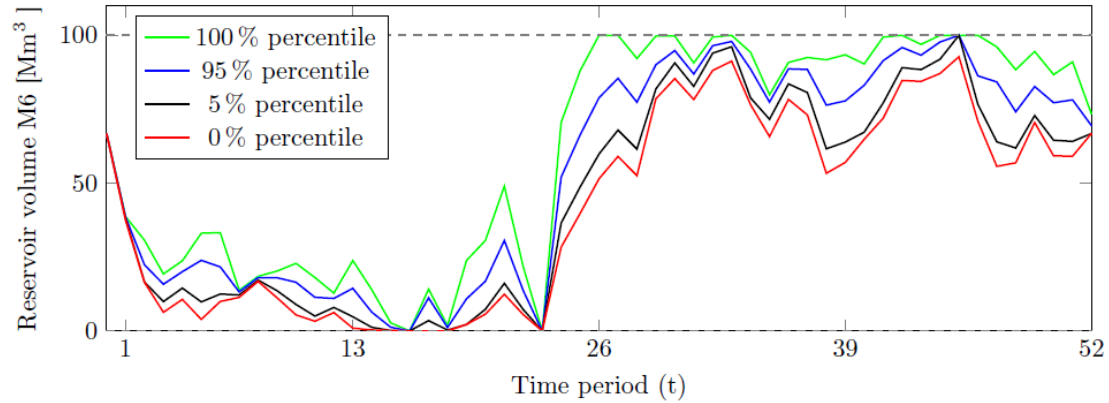
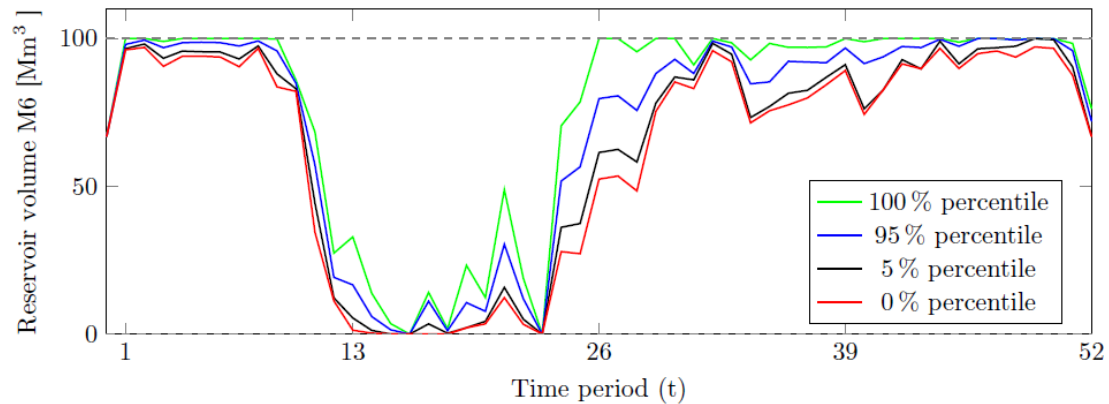


Figure 4: Optimal slope matrix for discharge from reservoir M6

# Inclusion of head corrections



(a) Reservoir trajectories M6 prior to head corrections

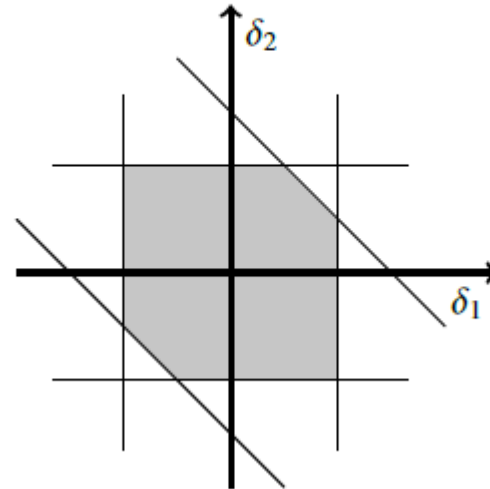


(b) Reservoir trajectories M6 after head corrections

# Inclusion of uncertainty

- Uncertainty polytope
  - Box Uncertainty
  - Budgeted Uncertainty sets

$$\begin{aligned} -1 &\leq \delta_{ut} \leq 1 & u \in \mathbb{U}, t \in \mathcal{T} \\ -\Gamma_i^L &\leq \sum_{t \in \mathcal{T}} \delta_{ut} \leq \Gamma_i^U & u \in \mathbb{U}, \end{aligned}$$



# Mathematical transformation

$$\max \quad T^H \sum_{t \in \mathcal{T}} \beta_t \pi_t \sum_{r \in \mathcal{R}} \sum_{d \in \mathbb{D}} E_{rt}^d x_{rt}^d \quad (1)$$

$$\text{s.t.} \quad m_{r0} = M_r^0 \quad r \in \mathcal{R} \quad (2)$$

$$m_{rt} = m_{r(t-1)} + F_{rt} + T^S \sum_{d \in \mathbb{D}} \left( \sum_{\rho \in \mathbb{C}_r^d} x_{\rho t}^d - x_{rt}^d \right) \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (3)$$

$$\underline{M}_{rt} \leq m_{rt} \leq \overline{M}_{rt} \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (4)$$

$$L_{rt}^q \leq E_{rt}^q x_{rt}^q \leq U_{rt}^q \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (5)$$

$$L_{rt}^p \leq E_{rt}^p x_{rt}^p \leq U_{rt}^p \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (6)$$

$$\underline{D}_{rt} \leq x_{rt}^q + C_{rt}^B \leq \overline{D}_{rt} \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (7)$$

$$x_{rt}^s \geq 0 \quad r \in \mathcal{R}, t \in \mathcal{T} \quad (8)$$

$$\hat{x}_{rt}^q + \sum_{u \in \mathbb{U}} \sum_{\tau \in \mathcal{M}_t^u} K_{rt\tau u}^q \delta_{u\tau} \leq \frac{U_{rt}^q}{E_{rt}^q}, \quad r \in \mathcal{R}, t \in \mathcal{T}, \delta \in \mathcal{U}. \quad (14)$$

$$\max_{\delta} \left\{ \begin{array}{l} \sum_{u \in \mathbb{U}} \sum_{\tau \in \mathcal{M}_t^u} K_{rt\tau u}^q \delta_{u\tau} \\ \text{s.t. } \sum_{u \in \mathbb{U}} \sum_{\tau \in \mathcal{T}} H_{ju\tau} \delta_{u\tau} \leq h_j, \quad \forall j : \mu_{rtj}^{Uq} \end{array} \right\} \leq \frac{U_{rt}^q}{E_{rt}^q} - \hat{x}_{rt}^q \quad r \in \mathcal{R}, t \in \mathcal{T}$$

$$\min_{\mu^{Uq}} \left\{ \begin{array}{l} \sum_j h_j \mu_{rtj}^{Uq} \\ \text{s.t. } \sum_j H_{ju\tau} \mu_{rtj}^{Uq} = K_{rt\tau u}^q, \quad u \in \mathbb{U}, \tau \in \mathcal{M}_t^u : \delta_{u\tau} \\ \sum_j H_{ju\tau} \mu_{rtj}^{Uq} = 0, \quad u \in \mathbb{U}, \tau \notin \mathcal{M}_t^u : \delta_{u\tau} \\ \mu_{rtj}^{Uq} \geq 0, \quad \forall j \end{array} \right\} \leq \frac{U_{rt}^q}{E_{rt}^q} - \hat{x}_{rt}^q \quad r \in \mathcal{R}, t \in \mathcal{T}.$$

$$\begin{aligned} \sum_j h_j \mu_{rtj}^{Uq} &\leq \frac{U_{rt}^q}{E_{rt}^q} - \hat{x}_{rt}^q, & r \in \mathcal{R}, t \in \mathcal{T} \\ \sum_j H_{ju\tau} \mu_{rtj}^{Uq} &= K_{rt\tau u}^q, & r \in \mathcal{R}, t \in \mathcal{T}, u \in \mathbb{U}, \tau \in \mathcal{M}_t^u \\ \sum_j H_{ju\tau} \mu_{rtj}^{Uq} &= 0, & r \in \mathcal{R}, t \in \mathcal{T}, u \in \mathbb{U}, \tau \notin \mathcal{M}_t^u \\ \mu_{rtj}^{Uq} &\geq 0, & r \in \mathcal{R}, t \in \mathcal{T}, j. \end{aligned}$$