

Application of OMA for Low-Frequency Modes Detection in FOWT: Numerical Study on OC4-DeepCwind Semi-Submersible

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- Floating Offshore Wind Turbines (FOWTs) have huge potential in harvesting wind energy for sites with deeper water depth (more than 50m) [1].
 - However, their commercialization has been hindered by high **operational and** maintenance costs (OPEX) [2].

2 Scope of Research

- The **dynamics** of mooring systems, floating platform and wind turbine are more complex, leading to greater uncertainties and higher costs [3].
 - Structural Health Monitoring (SHM) systems can mitigate these uncertainties and reduce OPEX cost.



BEL-Float

Catalyzing the Belgian industrial expertise in floating wind through academic innovation

3 Research Question

Can we reliably detect the platform **low-frequency** rigid body modes (e.g., surge, sway..) using **Operational Modal Analysis (OMA)**?

3 Methodology 3.2 PSD & Stabilization diagram 3.1 Time-domain Analysis (OpenFAST) Low-frequency Design values FA1 peak Tp 10 s





Conclusion

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Low-frequency and 1st **tower** modes are estimated across the LCs. Higher damping values of surge mode are noticed compared to FA1. **Rotor** harmonics and **wave** frequencies are also visible in the chart. 5.

- Window length above 300s is needed for the modal parameter estimation.
- Frequency band of 0-1 Hz yielded a good estimation of the low-frequency modes.
- Surge and Sway are the most sensitive modes to the OMA settings for accurate detection.
- Placing accelerometers in platform is essential to detect the FOWT motions, particularly yaw.
- The tracking chart shows the low-frequency modal properties are sensitive to the specific LC.

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References

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