

Dynamic cable cost optimisation using genetic algorithm for lazy wave, tethered lazy wave and Caroline Valenchon¹, Florian Castillo¹, Jean-Christophe Gilloteaux¹ Suspended configurations

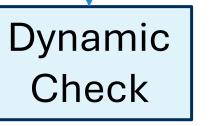


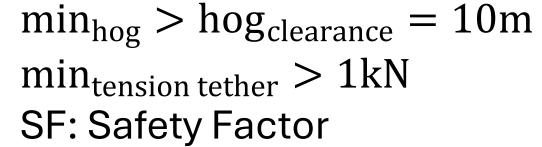
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The dynamic cable system significantly impacts the total cost of a floating offshore wind (FOW) farm, with two main configurations currently in use or under investigation. In shallow to medium water depths, (tethered) lazy wave configurations are employed, where the cable hangs in the water column from the floater or floating substation. In deeper waters, suspended configurations are emerging as a cost-effective solution, allowing the cable to hang between the FOWTs high in the water column through strategic positioning of buoyancy modules. Beyond water depth, optimal configurations depend on numerous factors, leading to a highly time-consuming and iterative design process. The goal is to develop a code to find an optimized configuration in term of cost, allowing to compare (tethered) lazy wave to suspended configuration for cost.

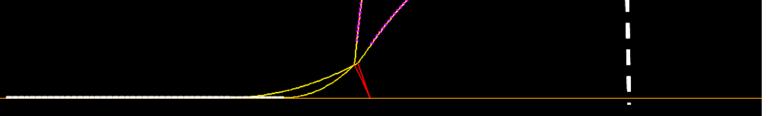
OPTIMIZATION PROCESS

Design space	Fitness function	Optimization performed	NEAR and FAR definition:
	$f = C_{cable} + C_{BM} + C_{ancillaries}$	with Genetic Algorithm (GA)	Extreme positions of the Hang-off point
Quasi static optimization	C _{cable} : cost of cable	Initial population	associated to the maximum FOWT
NEAR: FAR:	C _{BM} : cost of Buoyancy modules (BM)	Evaluation of individual:	offsets
Current Current	C _{ancillaries} : cost of ancillaries (tether, touchdown protection)	fitness function calculation	
+ offset + offset		Selection of parents	NEAR FAF
	$\square \max_{\text{tension}} < \text{SF} \times \text{MBL} = \text{Maximum Breaking Load}$	Crossing Selection of elites	
Optimized	min _{radius} > SF × MBR = Minimum Bending Radius	Mutation	
configuration	$min_{sag} > sag_{clearance} = 10m$	Next generation	
	10m		



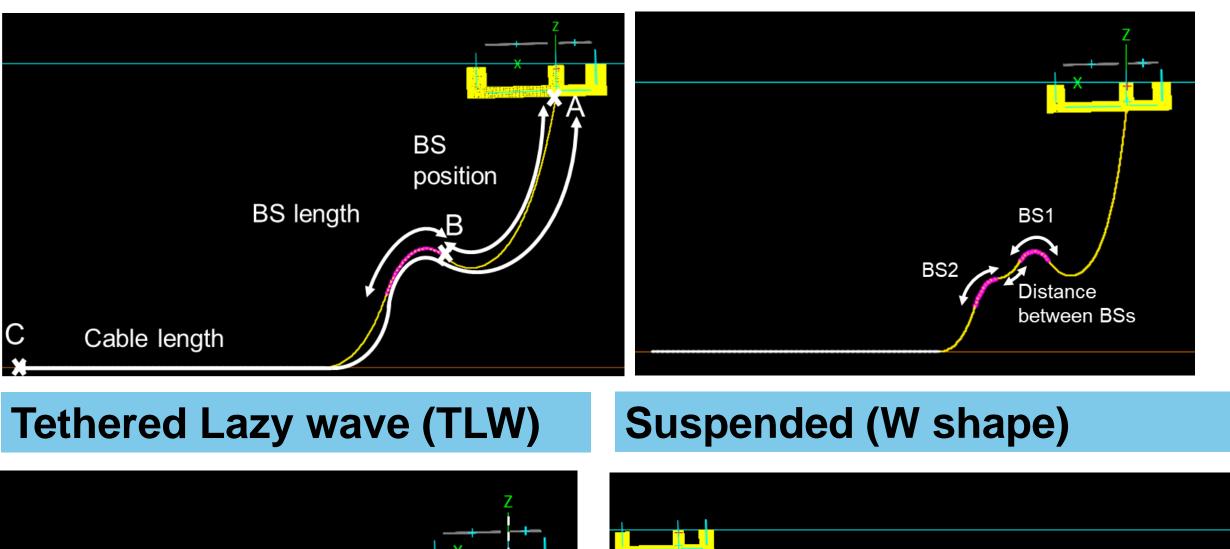






CONFIGURATIONS PRESENTATION

Lazy Wave / Double lazy wave (LW)



Parameters modified for all configurations:

- Cable length
- Position of the buoyancy section (BS)
- Number of buoyancy modules (BM)
- Ratio of buoyancy over mass use for outer diameter calculation of the BM

For Double LW:

corresponds

Tether length

For TLW:

Tether

Tether

Marine growth

60

30

20

195m

Thickness (mm)

Distance between two BSs

position on cable after BS.

anchor

Parameter

Current (at

sea surface)

Offset

Hs

Тр

horizontal position from (0,0)

position:

to

Unit

m

S

m/s

m

it

LC1

15.6

12

1.82

59

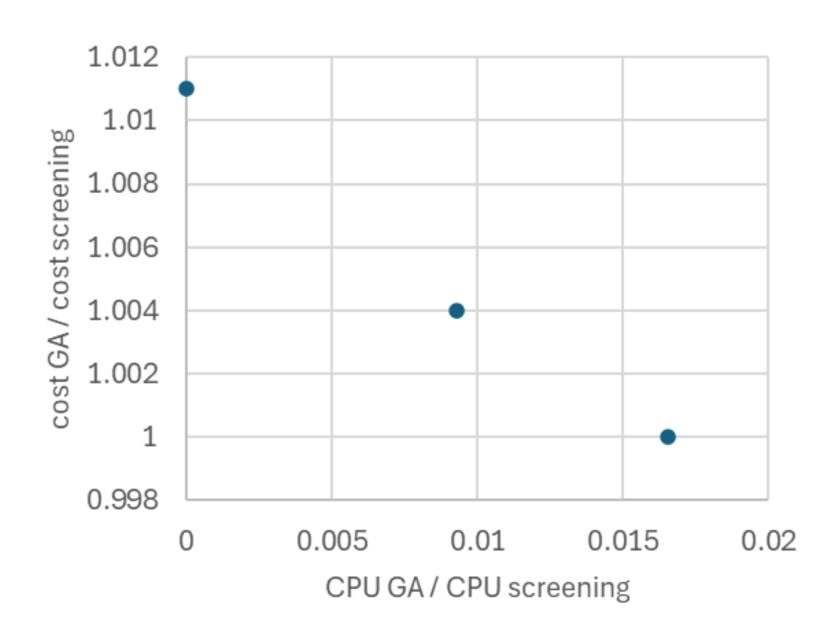
tether

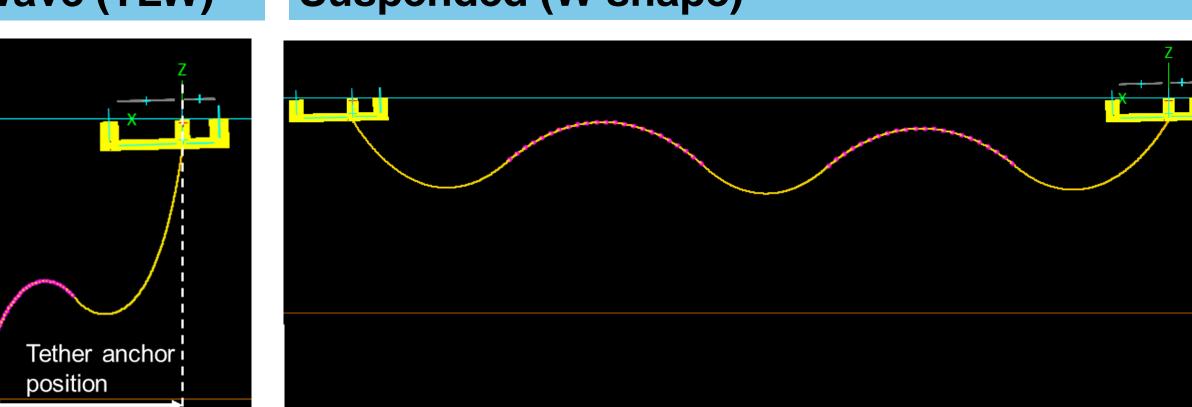
position:

- BM pitch
- BM width

VALIDATION – GA vs screening

Both methods provide similar costs. However, GA is far more efficient in term of calculation time leading to some cost saving on the design process.





CONDITIONS

after BS

Tether position

Tether length

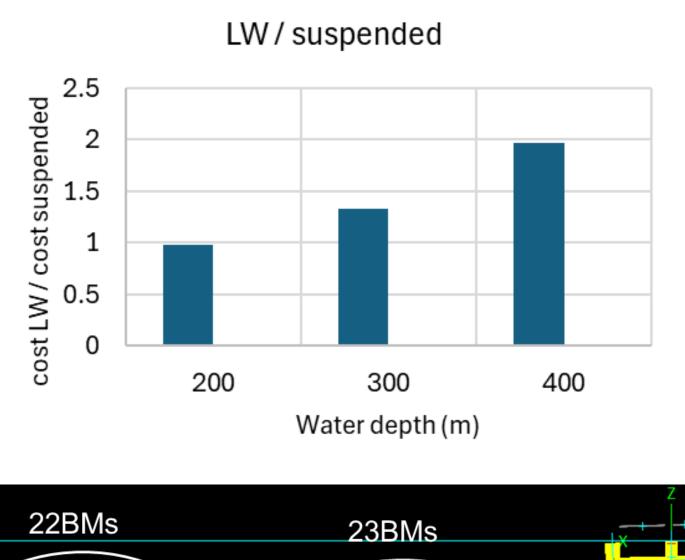
- Floating Wind Turbine: VolturnUS-S (from University of Maine) floater combined with a 15MW wind turbine (from NREL) [1]
- Conditions: West of Barra conditions [2]
- Marine growth: based on Norsok N-003 [3]
- EOL case: buoyancy loss (5%) considered
- LC1: used for TLW and suspended configuration
- LC2: used for LW and suspended configuration

RESULTS

Cost comparison: LW vs Suspended

4D distance between FOWT

Beyond 200m water depth, the suspended configuration becomes more costeffective than the LW configuration, mainly due to reduced cable length required.



872m

Water depth (m)

Up to 40m

Up to 100m

Below 100m

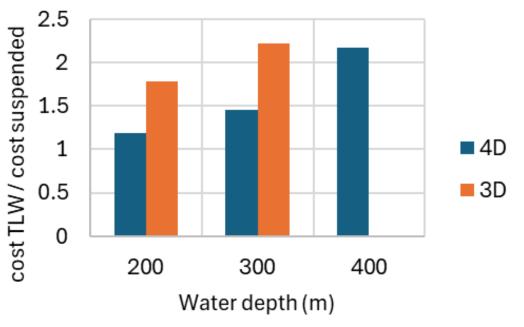
Cost comparison: TLW vs Suspended

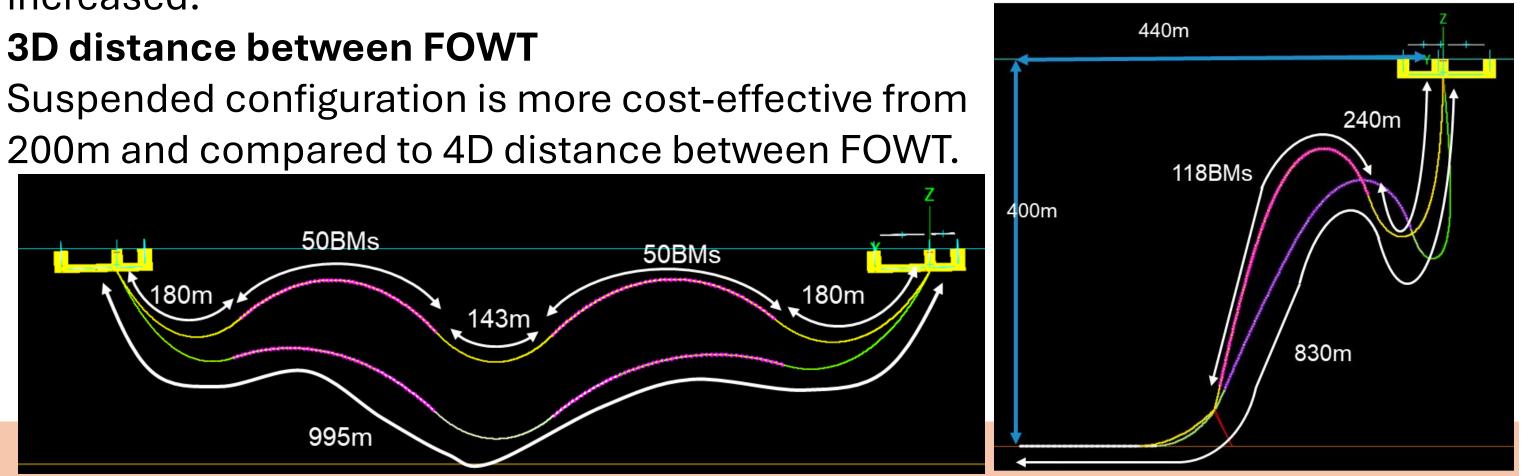
4D distance between FOWT

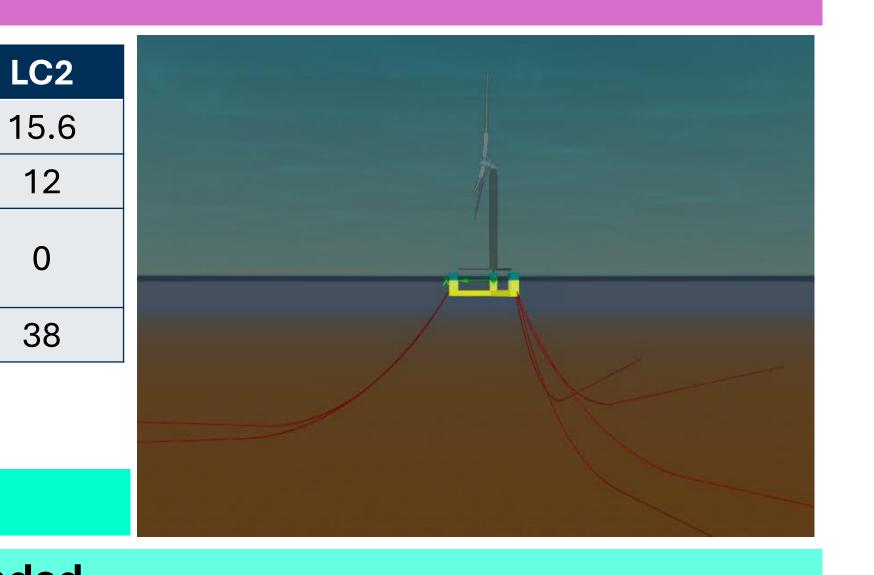
Suspended configuration is more cost effective from additional 200m ancillaries due to needed compared to LW.

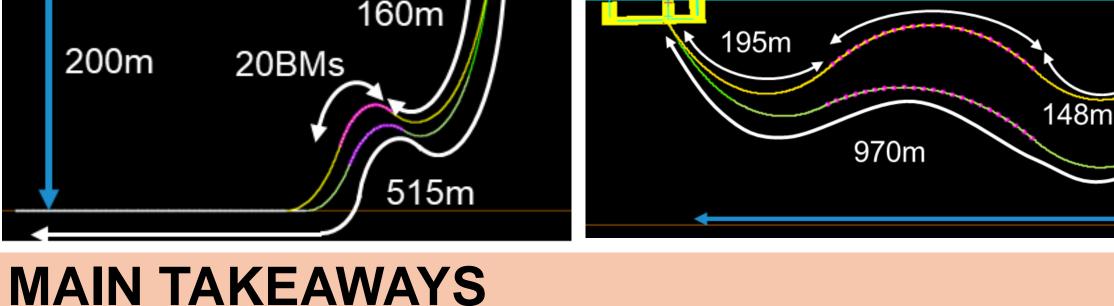
It is more difficult to find an acceptable suspended configuration at 200m due to close limit with seabed and max tension increased due to offset and current increased.

TLW / suspended









- Current has a small impact on the results for suspended configurations
- As distance between WT increases it is more difficult to find acceptable solutions for suspended configurations: for 5D and 7D, no configurations were found with the current marine growth profile
- Marine growth has a high impact on finding suitable suspended configurations. Moreover, as the distance increases, the compensation of tension by buoyancy modules is limited by the hog clearance with sea level. For long distances between wind turbine, a double BS configuration is not suited.

ACKNOWLEDGEMENT

Increasing the number of buoyancy sections could be the solution to remove the hog clearance issue. For the suspended configuration, an additional parameter, the number of buoyancy sections, will be added in the new version of the code.

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[1] C. Allen, et al, Definition of the UMaine VolturnUS-S Reference Platform Developed of the IEA Wind 15-Megawatt Offshore Reference Wind Turbine, 2020 [3] Norsok Standard, Actions and action effects, N-0003, 2007 [2] Corewind, D1.2 Design Basis, 2019